

## One-Dimensional Motion

The position of the particle on the one-dimensional axis can change with time. Therefore, there exists a function that determines the position at any moment of time. (If you need more information about the term "function", see [http://en.wikipedia.org/wiki/Function\\_%28mathematics%29](http://en.wikipedia.org/wiki/Function_%28mathematics%29).) We call it the position function. If the position axis is  $x$  and time is  $t$ , the position function will be  $x(t)$ .

Its first and second time derivatives are also functions with well-known names.  $\frac{dx}{dt} \stackrel{\text{def}}{=} v$  is called *speed*,  $\frac{d^2x}{dt^2} = \frac{dv}{dt} \stackrel{\text{def}}{=} a$  is called *acceleration*.

Here we will study only three types of motion:  $x = \text{const}$ ,  $v = \text{const}$ ,  $a = \text{const}$ .

1.  **$x = \text{const}$** . It is clear that any derivative of  $x$  will be zero. Therefore,  $v = 0$ ,  $a = 0$ . The particle is not changing its position, i.e. it is at rest at all times. This case corresponds to **no motion**; the particle is **resting**.
2.  **$v = \text{const}$** . Acceleration is therefore zero, but the position function is linear:

$$x = \int v dt = v \int dt = vt + x_0 \quad (1)$$

where  $x_0$  is the constant of integration corresponding to the particle's initial position. This case is called **uniform motion**.

3.  **$a = \text{const}$** . Integrating up to  $v$  and further to  $x$ , we have

$$v = \int a dt = a \int dt = at + v_0 \quad (2)$$

$$x = \int v dt = \int (at + v_0) dt = \int at dt + \int v_0 dt = a \int t dt + v_0 \int dt = \frac{at^2}{2} + v_0 t + x_0 \quad (3)$$

This case is called accelerated motion and the speed and position functions for it are often called the basic kinematic equations, since accelerated motion is extremely widespread in kinematics.

$$v = v_0 + at \quad (4)$$

$$x = v_0 t + \frac{at^2}{2} \quad (5)$$

In the last one the initial position  $x_0$  is omitted because it is almost always convenient to put the zero of your coordinate into the place where motion begins, thus making  $x_0 = 0$ .

*Average speed* on a certain interval of motion is defined as the ratio of the length of the interval and the

time during which it was covered by motion:

$$\langle v \rangle = \frac{x_{total}}{t_{total}} \quad (6)$$

**Example problem.** A car driver traveling at speed  $v_0$  saw a speed bump from the distance  $s$  and applied the brakes. He decelerated with the magnitude  $a$ . At what speed did he go over the bump?

**Solution.** This is accelerated motion. Putting the origin at the place where he saw the bump (and thus making the initial position zero), we write the kinematic equations:

$$v = v_0 - at, \quad s = v_0 t - \frac{at^2}{2} \quad (7)$$

Notice the minus sign (if  $a$  is the *magnitude*, a positive quantity, you must not forget the minus if the driver *decreased* the speed). This is a system of 2 equations with 2 unknowns:  $t$ , the time of motion from the origin to the bump, and  $v$ , the speed which we are looking for. Solving the 2<sup>nd</sup> equation for  $t$  (it is quadratic)

$$\frac{a}{2}t^2 - v_0 t + s = 0; \quad t = \frac{v_0 \pm \sqrt{v_0^2 - 2as}}{a} \quad (8)$$

and substituting  $t$  into the first equation, which is already a ready-made solution for  $v$ , we get

$$v = \sqrt{v_0^2 - 2as} \quad (9)$$

We had to throw out the solution with the plus sign because it gave us a negative value and thus did not correspond to the situation. Also notice that  $v_0^2 - 2as$  must be positive, otherwise the driver will stop before the bump is reached.

**Additional question.** What is the average speed of the car on the whole distance to the bump?

**Answer.** Average speed is total distance over total time. In this case, the distance is  $s$  and the time is

$$t = \frac{v_0 - \sqrt{v_0^2 - 2as}}{a} \quad (10)$$

so the average speed is

$$\langle v \rangle = \frac{as}{v_0 - \sqrt{v_0^2 - 2as}} \quad (11)$$